

Anisotropy Creases Delineate White Matter Structure in Diffusion Tensor MRI

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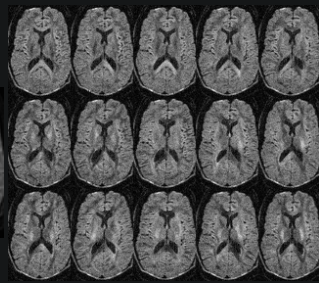
² Scientific Computing and Imaging Institute
University of Utah



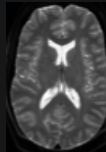
Diffusion weighted imaging, tensor imaging

DWI

A_i



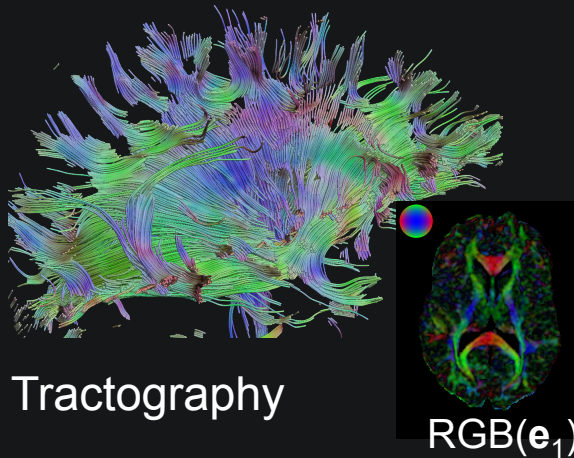
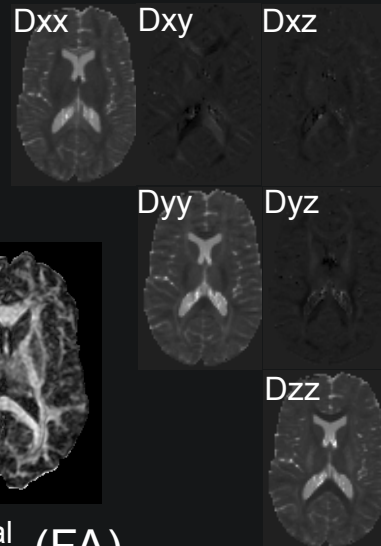
A_0



$$A_i(b, \mathbf{g}) = A_0 e^{-b \mathbf{g}_i^T \mathbf{D} \mathbf{g}_i}$$

(Basser 1994)

DTI

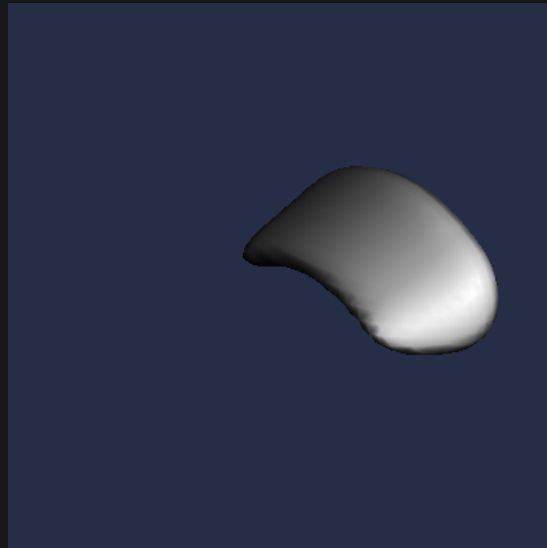
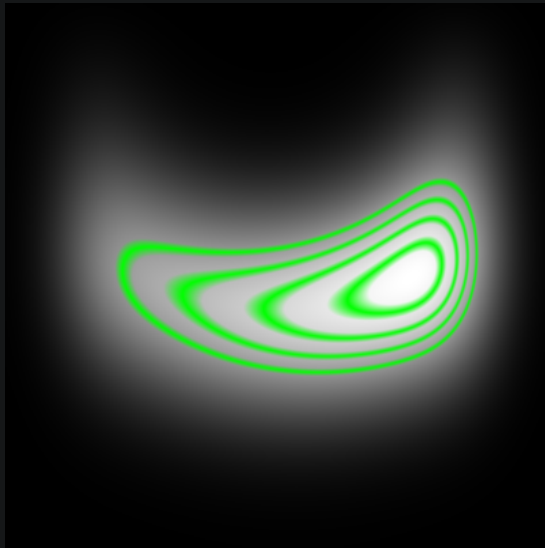


Tractography

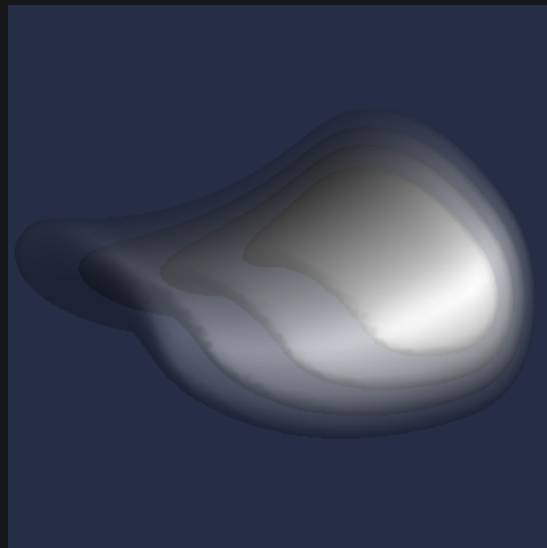
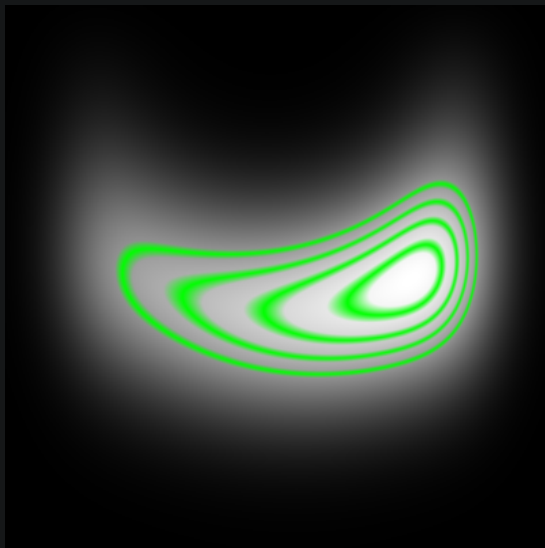
RGB(\mathbf{e}_1)

fractional anisotropy (FA)

Isosurfaces show global structure ...



Isosurfaces show global structure ...



.... but don't always show salient structure

Creases!

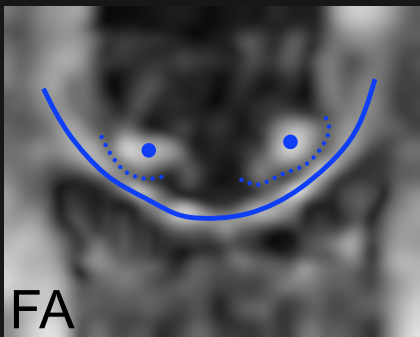


Creases (ridges and valleys) do capture salient structure

Creases for DTI?



- Goal: model large-scale white matter structures
 - Robust + Repeatable
 - Few or Zero Parameters
 - “Sulci for white matter”

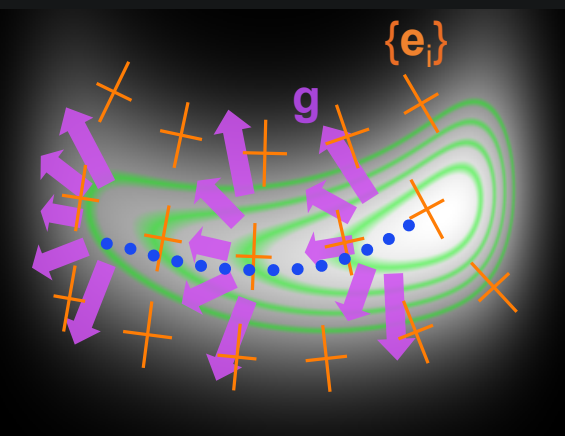


- Basic Idea: Creases of FA
 - Ridges: “cores”
 - Valleys: interfaces
 - Shape, not connectivity

Rest of talk

- Mathematical definition of creases
- Measurement by convolution
- Analytical differentiation of FA
- Slice inspection (2-D results)
- Modified Marching Cubes for surface
- 3-D results

Crease feature definition (Eberly 1994)



Constrained extremum

Gradient \mathbf{g}

Hessian eigensystem \mathbf{e}_i, λ_i

Crease: \mathbf{g} orthogonal to one or more \mathbf{e}_i

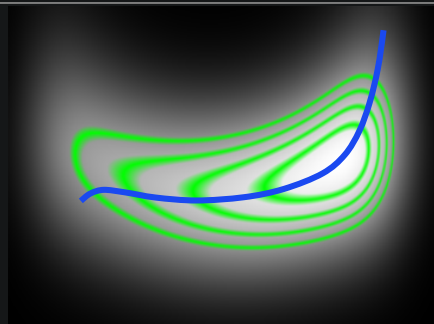
Eigenvalue gives strength

Ridge surface: $\mathbf{g} \cdot \mathbf{e}_3 = 0; \lambda_3 < \text{thresh}$

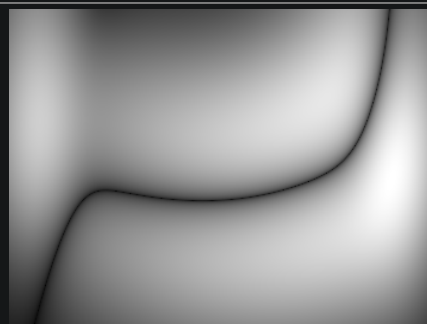
Ridge line: $\mathbf{g} \cdot \mathbf{e}_3 = \mathbf{g} \cdot \mathbf{e}_2 = 0; \lambda_3, \lambda_2 < \text{thresh}$

Valley surface: $\mathbf{g} \cdot \mathbf{e}_1 = 0; \lambda_1 > \text{thresh}$

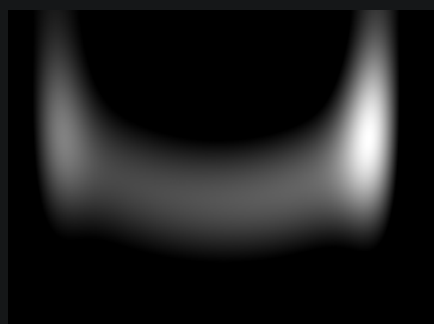
2-D Synthetic Scalar Example



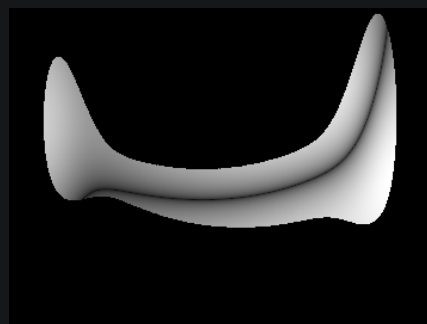
f



$|\mathbf{g} \cdot \mathbf{e}_3|$



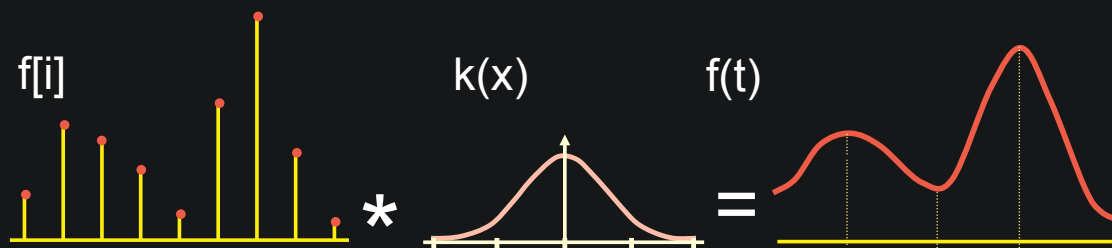
strength: $\max(0, -\lambda_3)$



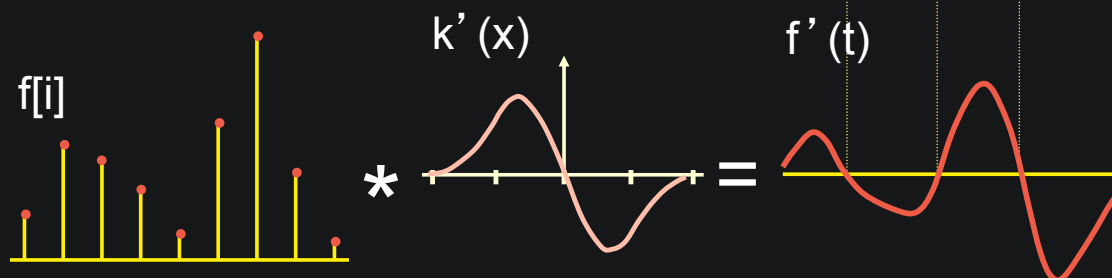
$-\lambda_3 > \text{thresh}$

Measurement (of scalars) by convolution

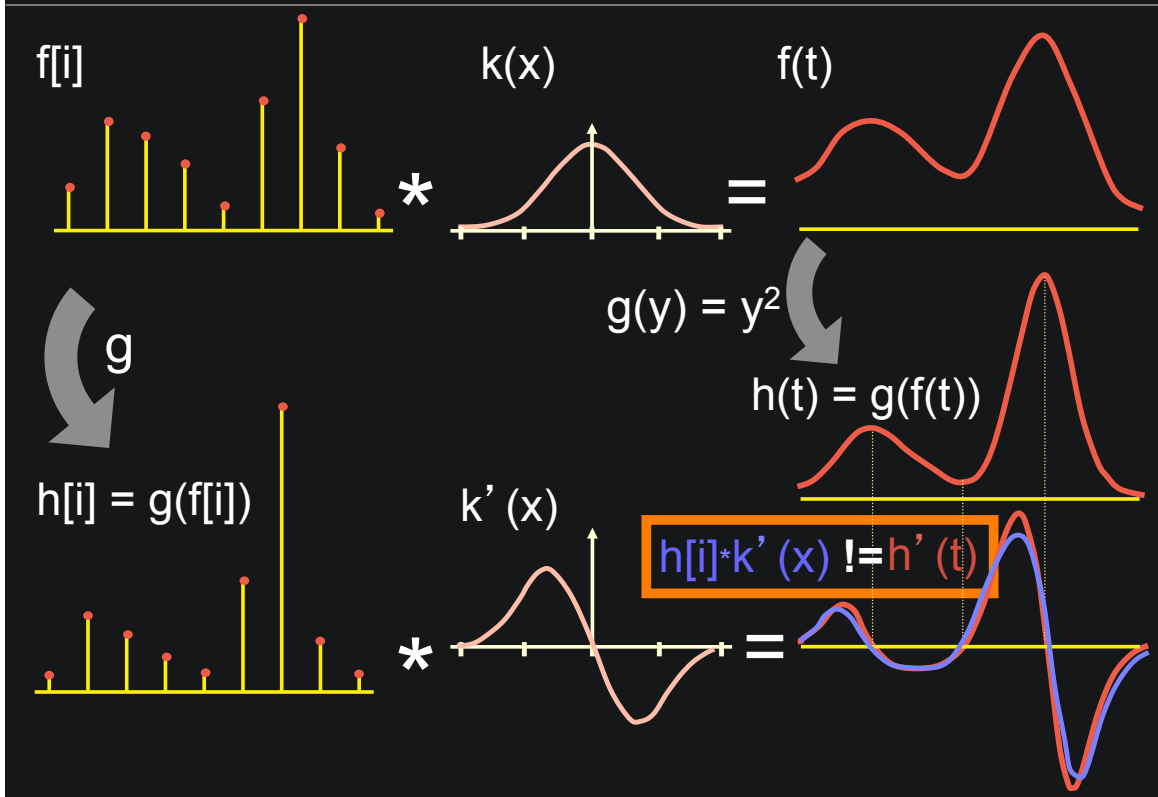
Continuous field: convolution of sampled coefficients with continuous reconstruction kernels



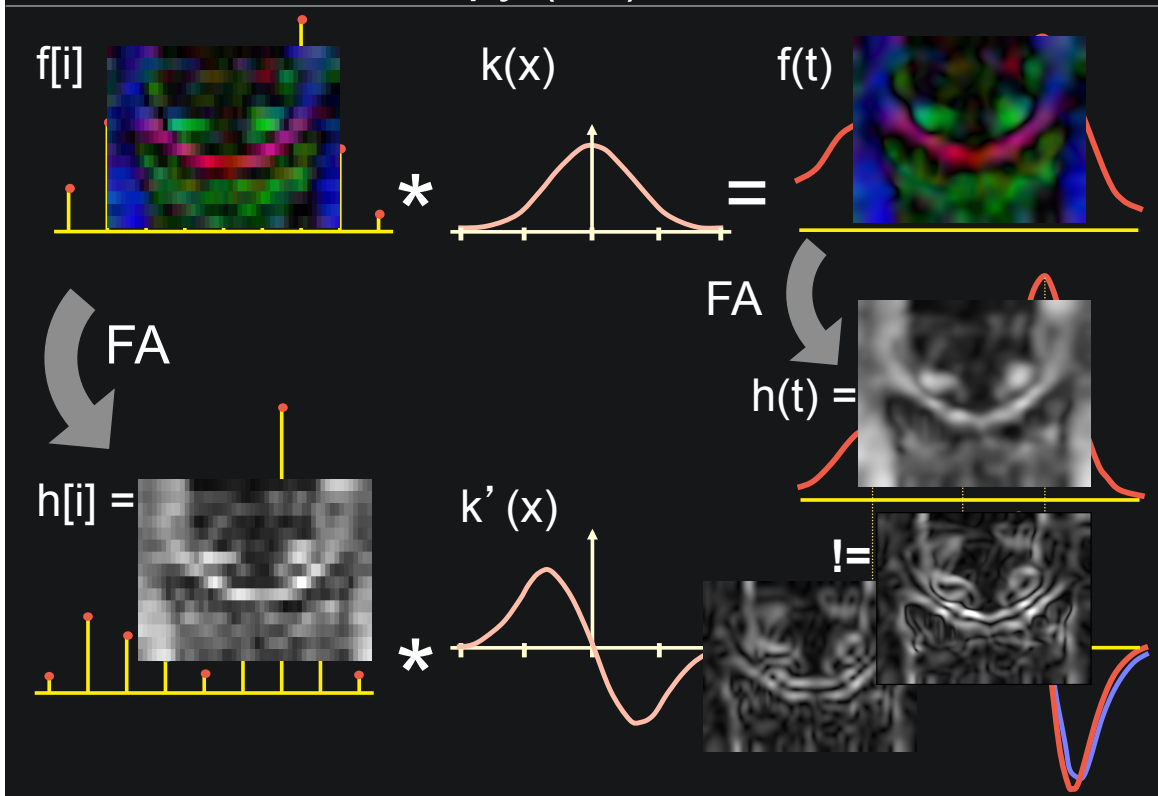
Differentiation: convolve w/ derivative of reconstruction kernel



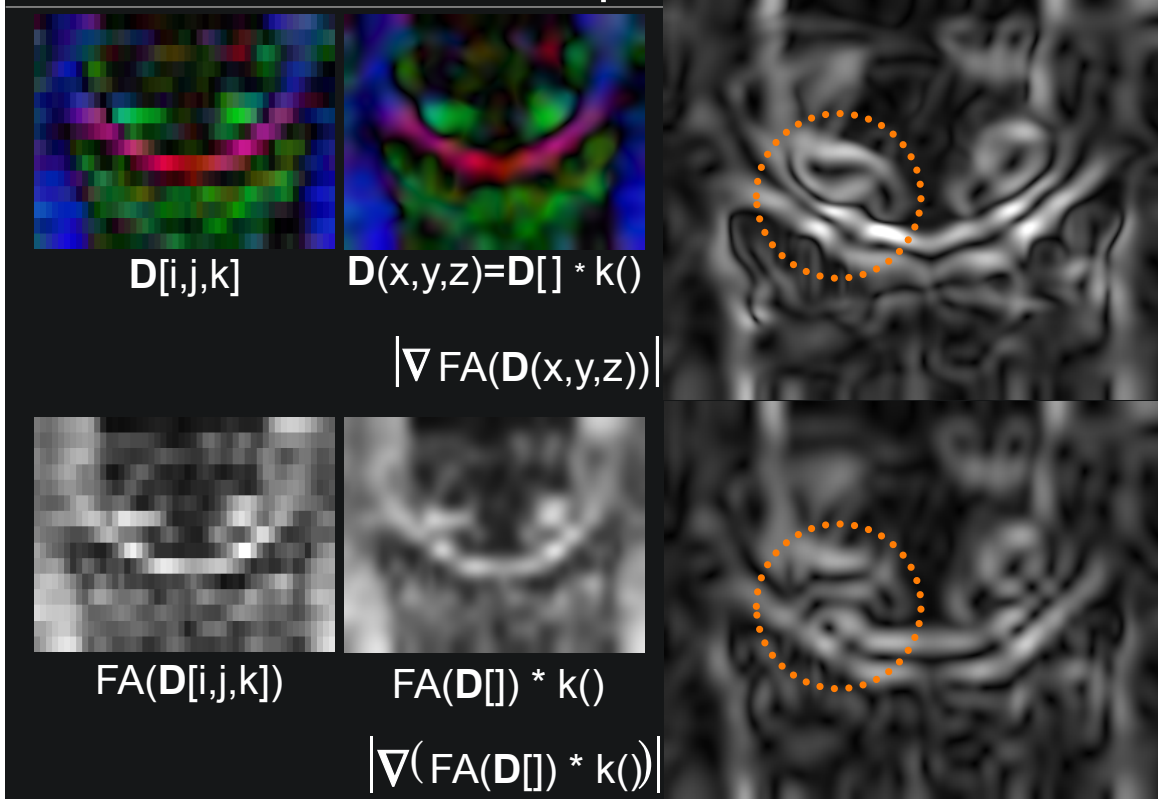
Non-linear transform of data



Fractional Anisotropy (FA) is non-linear



FA is non-linear, close-up



FA from invariants, from coefficients

$$FA \equiv \sqrt{\frac{3 D:D}{2 D:D}}$$

$$D = \mathbf{D} - \langle \mathbf{D} \rangle \mathbf{I} \quad \mathbf{D}:\mathbf{D} = \text{tr}(\mathbf{D}\mathbf{D}^T)$$

$$FA = 3 \sqrt{\frac{Q}{S}}$$

$$Q = \frac{S - J_2}{9} \quad J_2 = D_{xx}D_{yy} + D_{xx}D_{zz} + D_{yy}D_{zz} - D_{xy}^2 - D_{xz}^2 - D_{yz}^2$$

$$S = \mathbf{D}:\mathbf{D} = D_{xx}^2 + D_{yy}^2 + D_{zz}^2 + 2D_{xy}^2 + 2D_{xz}^2 + 2D_{yz}^2$$

$$\nabla J_2 = (D_{yy} + D_{zz})\nabla D_{xx} + (D_{xx} + D_{zz})\nabla D_{yy} + (D_{xx} + D_{yy})\nabla D_{zz} - 2D_{xy}\nabla D_{xy} - 2D_{xz}\nabla D_{xz} - 2D_{yz}\nabla D_{yz}$$

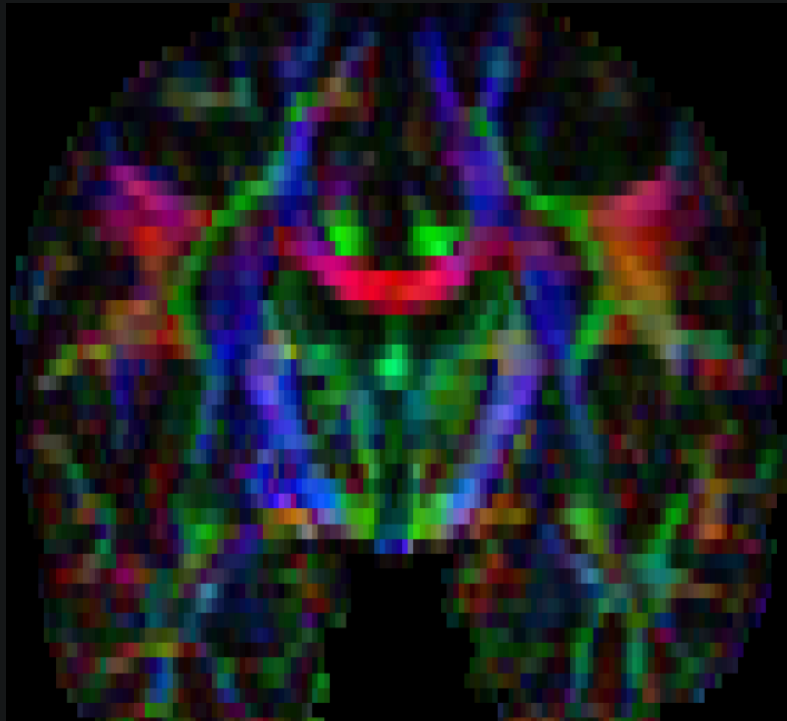
$$\nabla Q = \frac{\nabla S - \nabla J_2}{9}$$

$$\nabla S = 2D_{xx}\nabla D_{xx} + 2D_{yy}\nabla D_{yy} + 2D_{zz}\nabla D_{zz} + 4D_{xy}\nabla D_{xy} + 4D_{xz}\nabla D_{xz} + 4D_{yz}\nabla D_{yz}$$

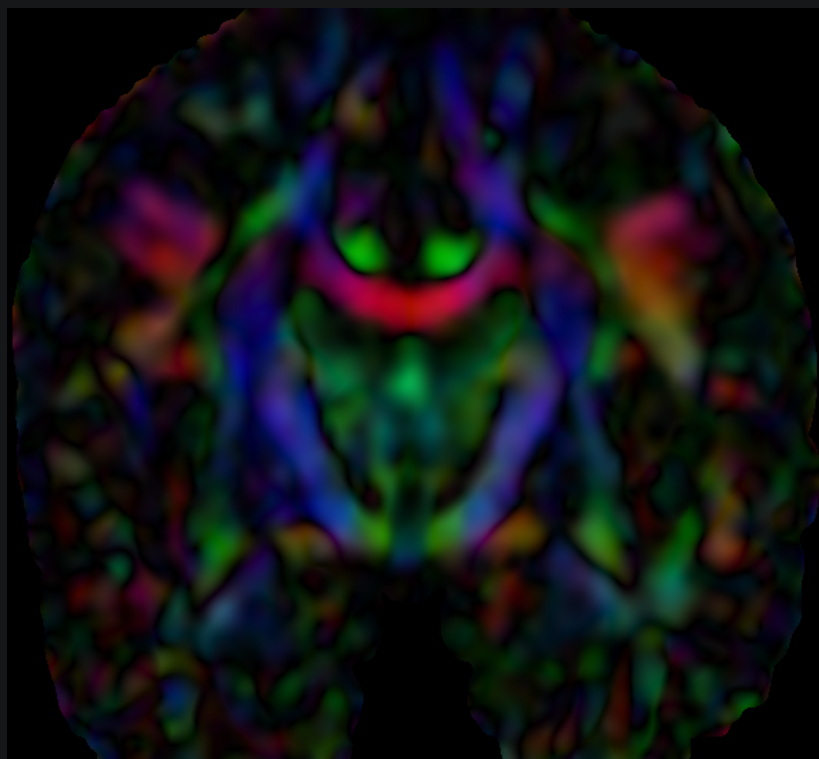
$$\nabla FA = \frac{3}{2} \left(\sqrt{\frac{1}{SQ}} \nabla Q - \sqrt{\frac{Q}{S^3}} \nabla S \right)$$

Hessian(FA) more complicated, but similarly derived

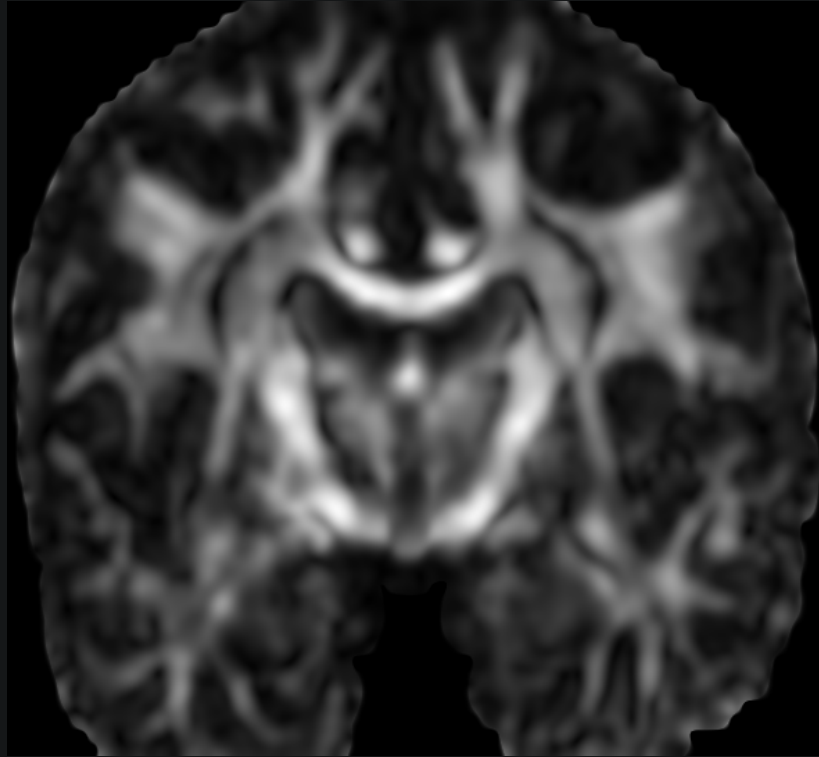
Slice Inspection: $\text{RGB}(\mathbf{e}_1)$ (original data)



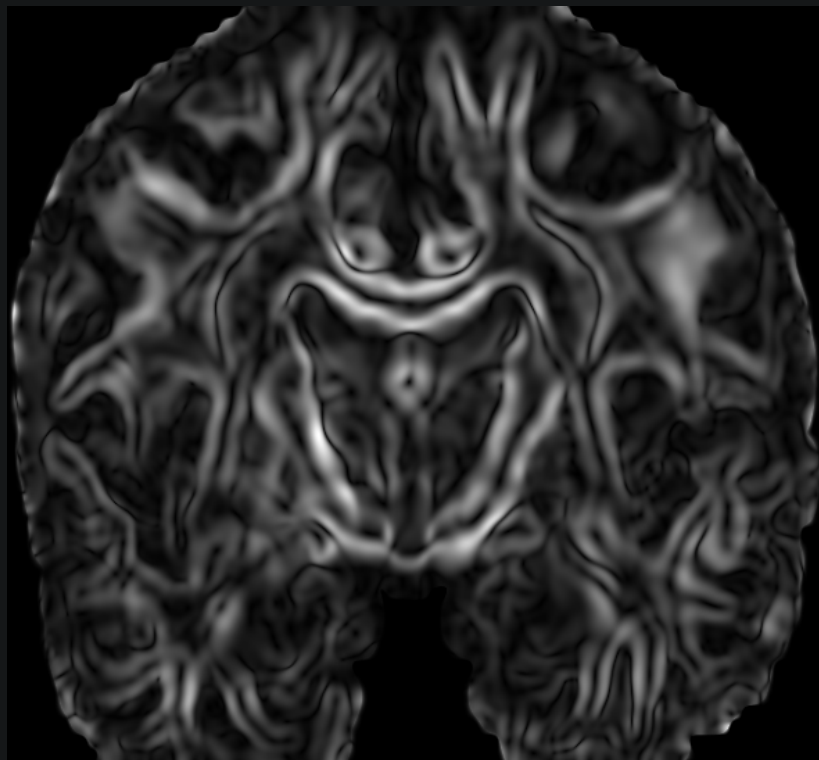
Slice Inspection: $\text{RGB}(\mathbf{e}_1)$



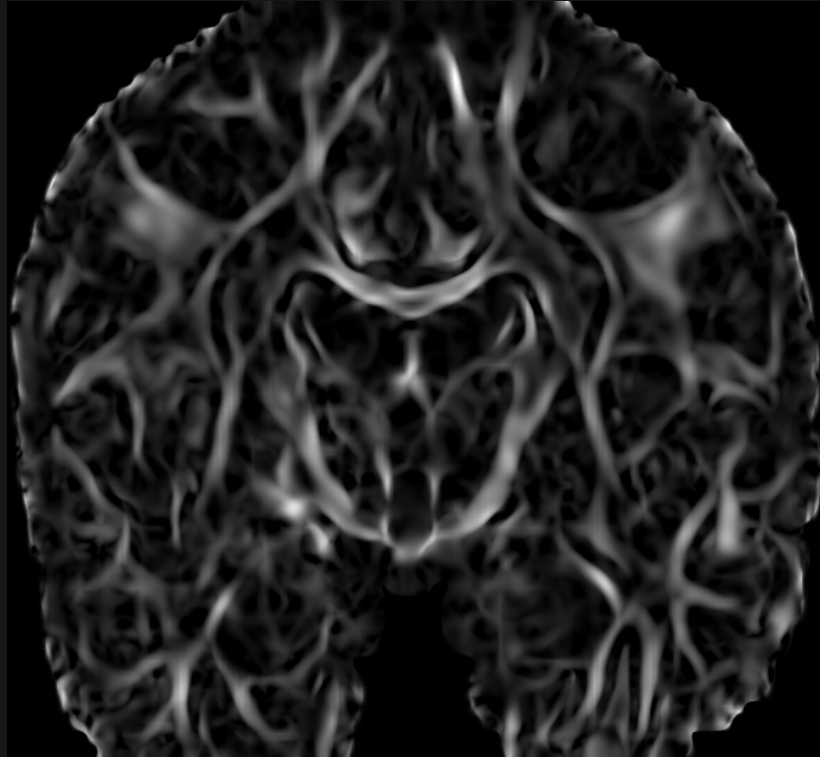
Slice Inspection: FA



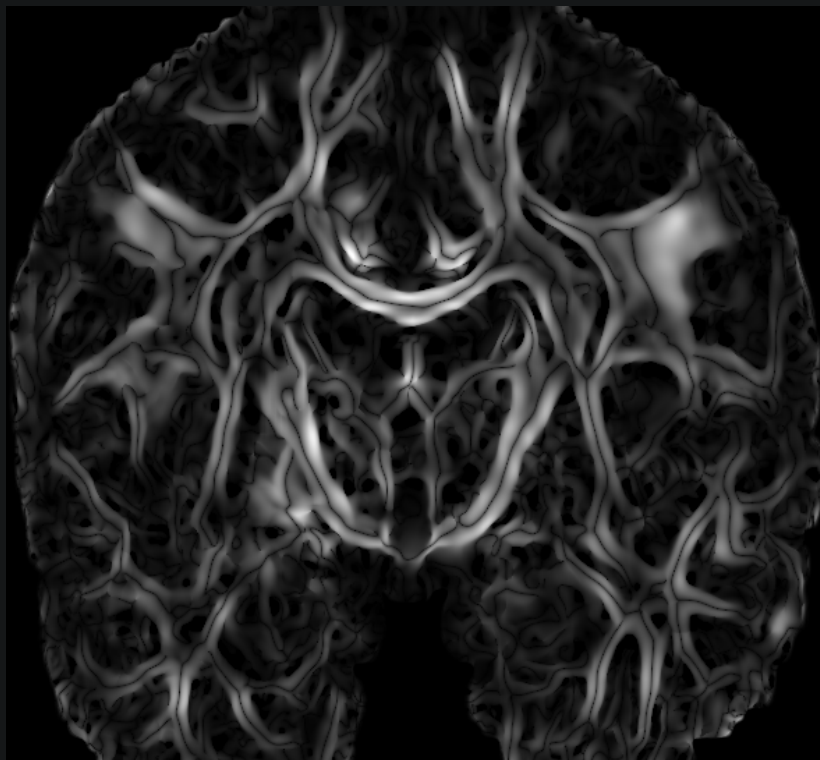
Slice Inspection: $|\nabla FA|$



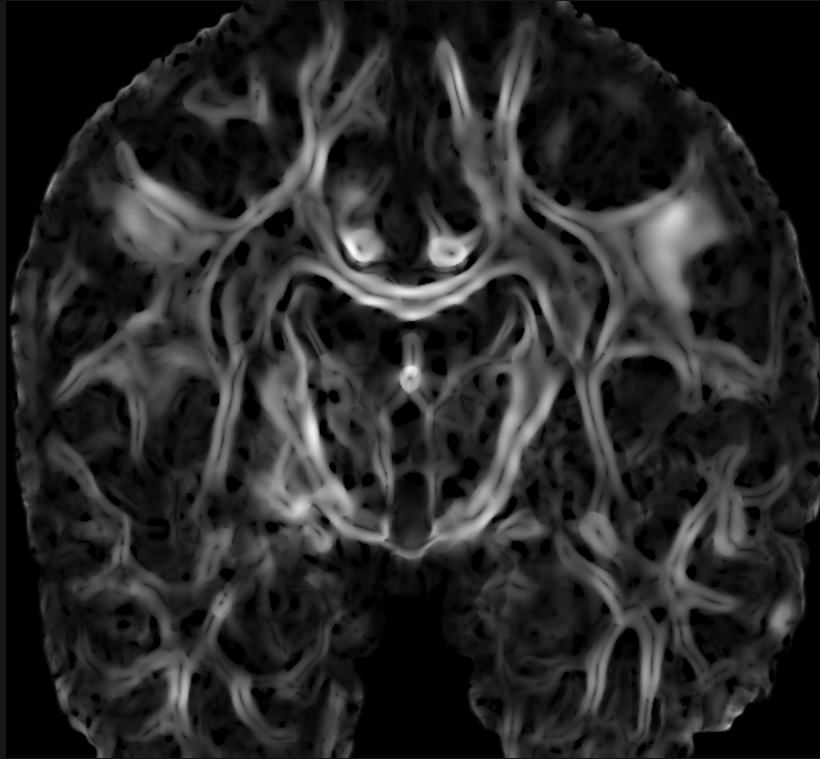
Slice Inspection: ridge strength: $\max(0, \lambda_3)$



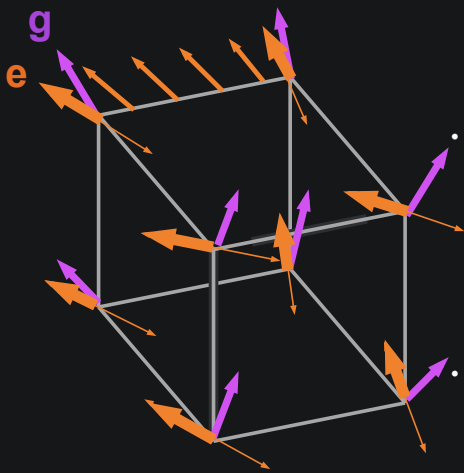
Slice Inspection: $|\mathbf{g} \cdot \mathbf{e}_3|$ (modulated by strength)



Slice Inspection: $\sqrt{(\mathbf{g} \cdot \mathbf{e}_3)^2 + (\mathbf{g} \cdot \mathbf{e}_2)^2}$

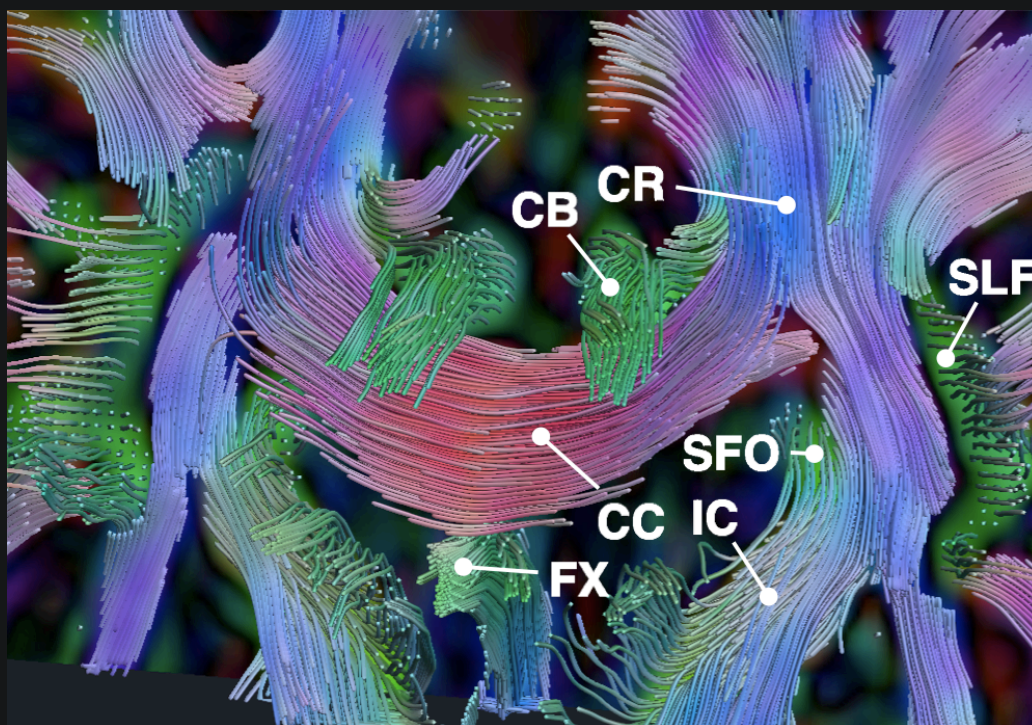


Modified Marching Cubes for Surfaces



- Crease surface is isosurface (zero-crossing) of $\mathbf{g} \cdot \mathbf{e}_i$, but...
- Eigenvectors lack sign: enforce intra-voxel sign consistency
- Propagate eigenvector at one corner to all others
- $\mathbf{g} \cdot \mathbf{e}$ dot products, then MC case table

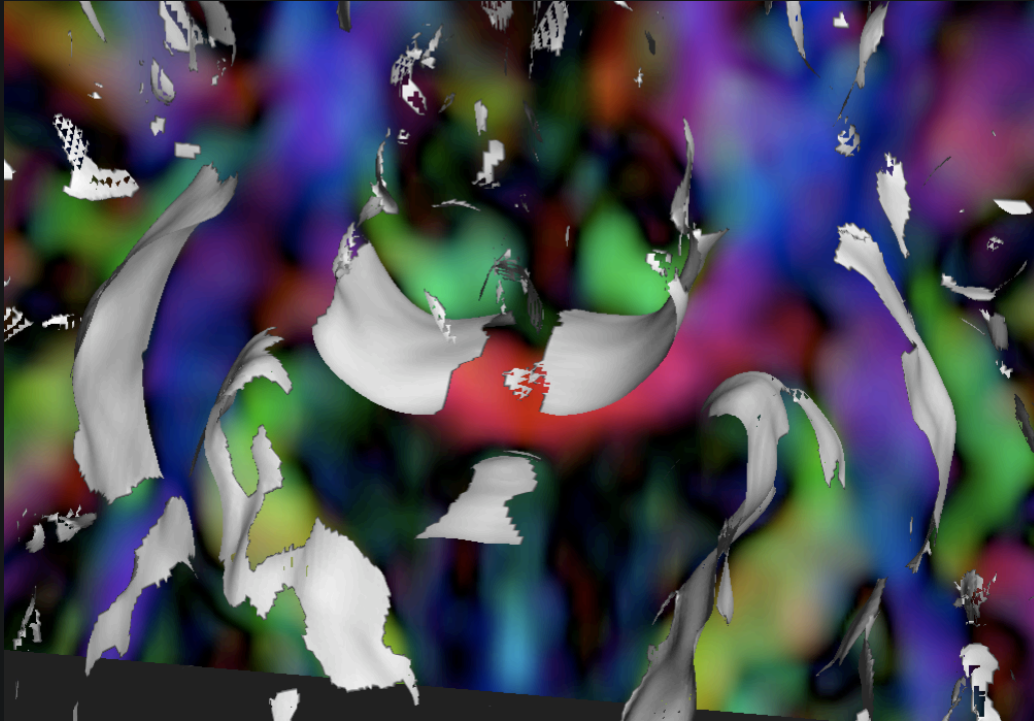
3-D Results: coronal fibers



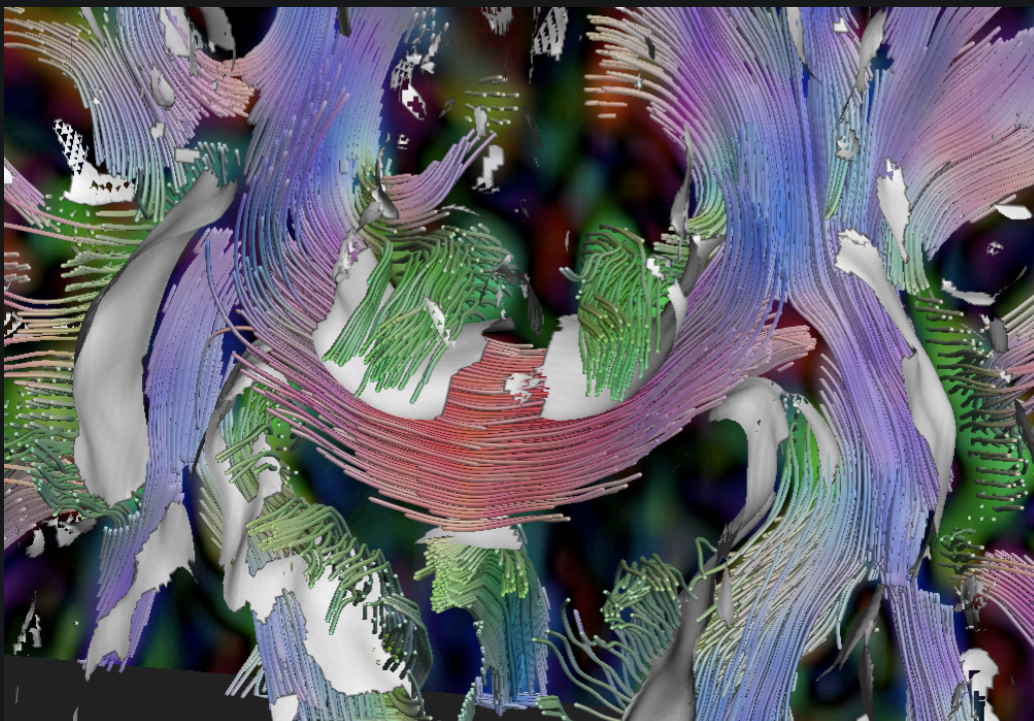
3-D Results: ridge surfaces



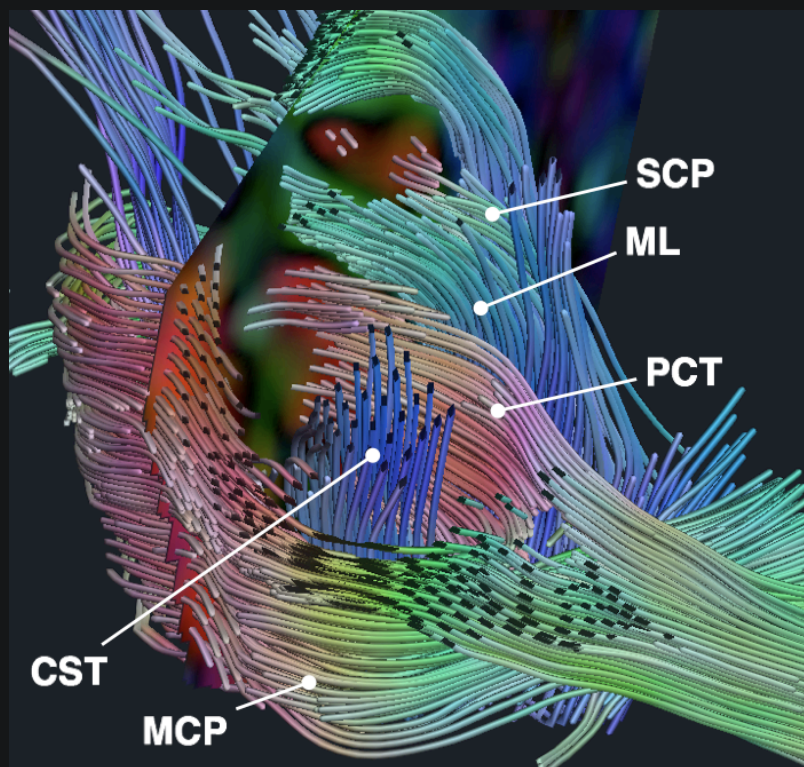
3-D Results: valley surfaces



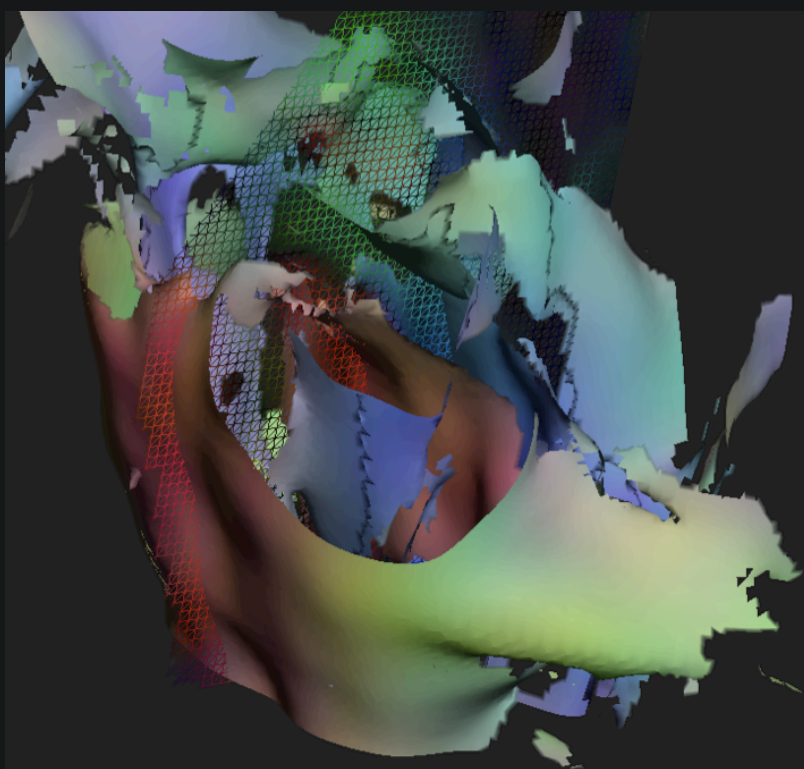
3-D Results: valley surfaces with fibers



3-D Results: brainstem fibers



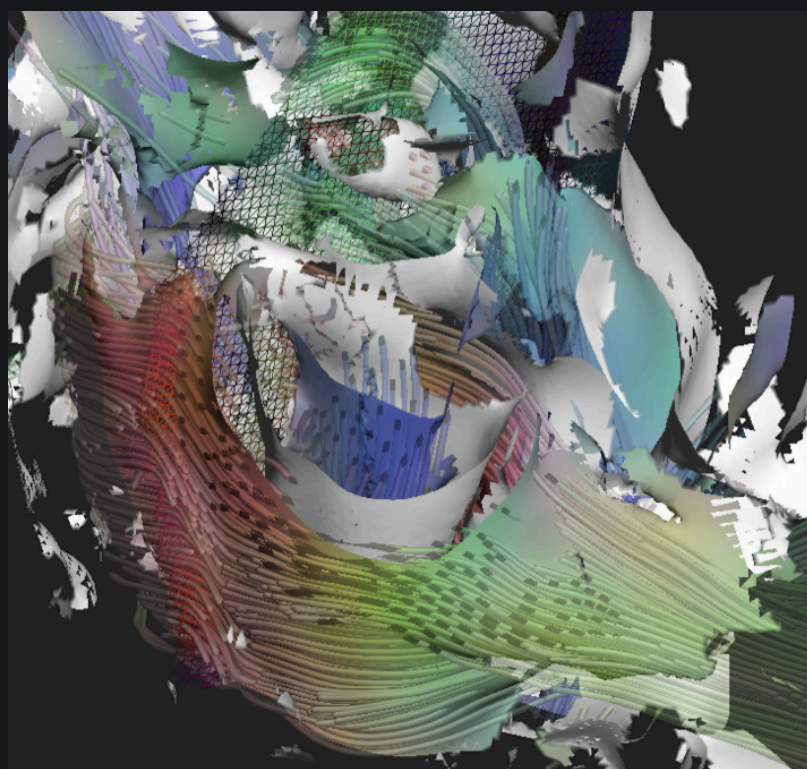
3-D Results: brainstem ridge surfaces



3-D Results: brainstem valley surfaces



3-D Results: combined results



Discussion & Ongoing Work

- Novel Aspects:
 - Application of computer vision to DTI
 - Extracting geometry from differential DTI structure
- Scale space: interfaces are easier than “cores”
- Tensor eigensystem orientation?
- Crease line extraction; line vs. surface decision
- Evaluation on more datasets
- Besides registration: Shape analysis, tracts as manifolds, assymetry measurement

Acknowledgements

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- URL for paper + software info:
- <http://lmi.bwh.harvard.edu/~gk/miccai06/>

thank you